30-meter cabin refurbishment for a large Field Of View: status of on-going study

S.Leclercq 28/04/2008

New Optics Specifications

- 1. FOV \geq 10' for bolometers, FOV \geq 7' for heterodynes.
- 2. Mirrors size < 1.6 m and surface accuracy ≤ 15 μ m RMS.
- 3. Optical systems fit in limited room (+ hardware & operator).
- 4. Number of optical elements as small as possible.
- 5. M3 rotating system efficient an simple.
- 6. Bolometer size $\approx \lambda + 5..10 \%$ & sample $\theta_{HPBW} = 1.03 \lambda/D \rightarrow 11.4..10.8$ ' on 8 inches wafer ($\Delta ImageSize \sim 5$).
- 7. Smallest cryostat window possible for bolometers (D < 18 cm).
- 8. Minimum cost \rightarrow no new M2 and all elements in receiver cabin.

Current optics versus proposition

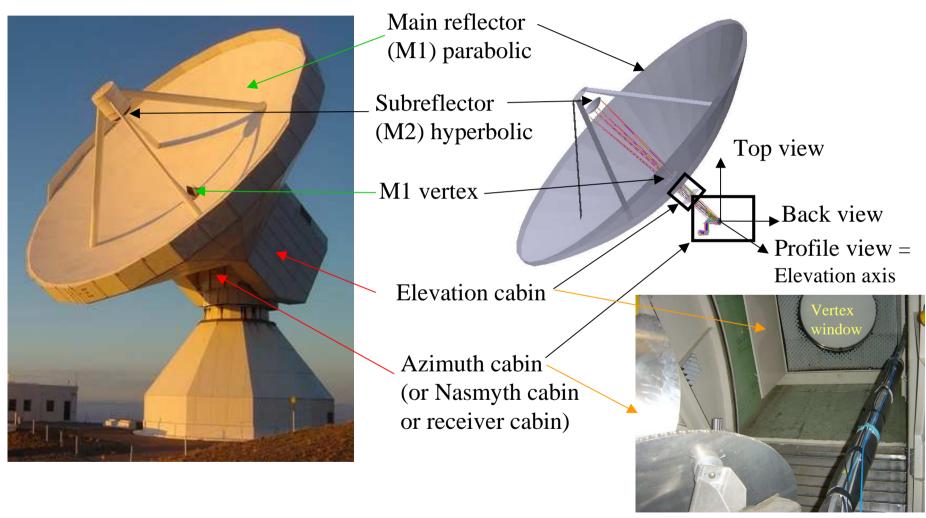
Current

- FOV = 4.5 arcmin available for both bolometers and heterodynes.
- 7 mirrors in cabin + 1 or 2 lens(es) for bolometers
- M≥3 flat
- M3 elliptic contour = 1040×740
- M4 elliptic contour = 920×650
- M3 rotate on elevation axis (Nasmyth)
- M3-M4 = 700 mm

Proposed

- FOV = 10 arcmin for bolometers,
 7.4 arcmin for heterodynes.
- 2 mirrors in cabin + 2 lenses for bolometers
- Mh≥3 flat, Mb>3 curved
- M3 elliptic contour = 1440×1200
- M4h elliptic contour = 1170×810
 M4b elliptic contour = 1070×990
- M5b elliptic contour = 980×930
- M3 Nasmyth for heterodyne, 2 axes of rotation for bolometers
- M3-M4h = 860 mmM3-M4b = 1500 mm

Reference frame for Zemax simulations

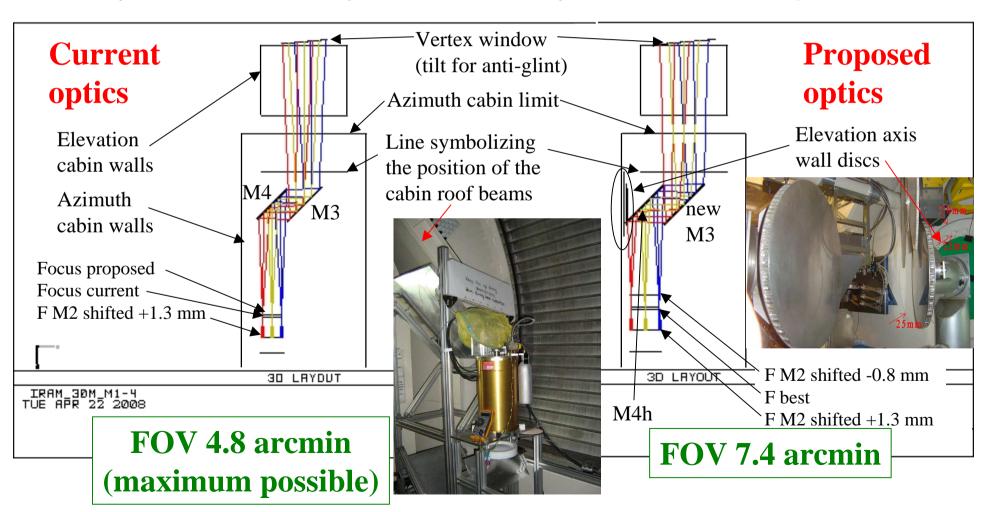


→ Simulation of the whole telescope (not equivalent lens)

Heterodynes optics: current vs proposed

Top view at 0 degree elevation angle

Blue rays = (+FOV/2;0), Green rays = (0;+FOV/2), Red rays = (-FOV/2;0), Yellow rays = (0;-FOV/2)



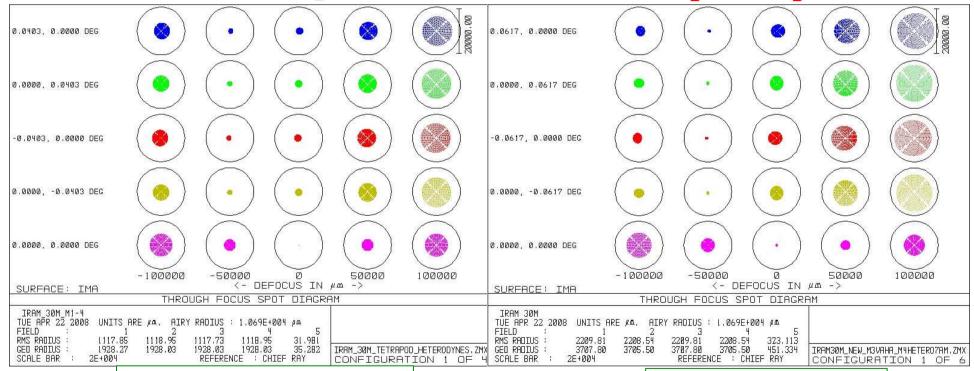
Through focus spot diagram, heterodynes

 λ =0.87mm Δ foc=5cm circle = Airy disc

Blue = (+FOV/2:0), Green = (0:+FOV/2), Red = (-FOV/2:0), Yellow = (0:-FOV/2), Magenta = (0:0)

Current optics

Proposed optics

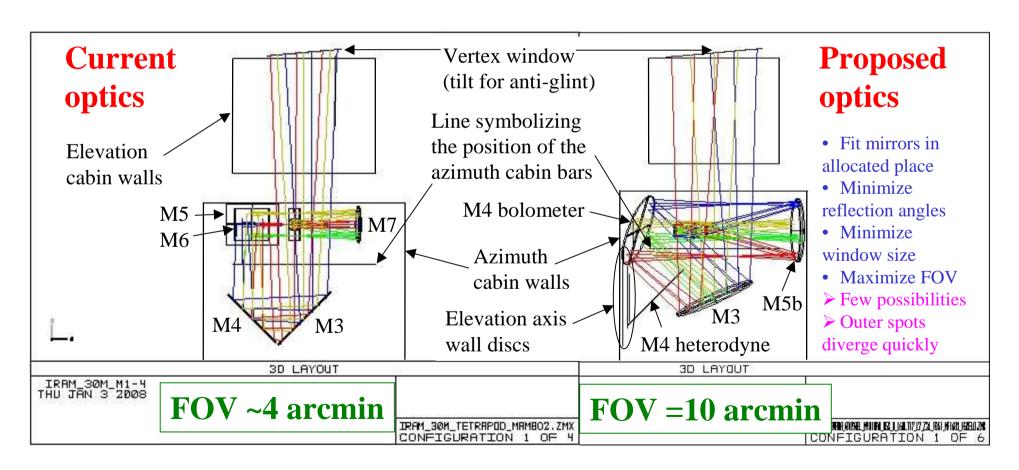


FOV 4.8 arcmin (maximum possible) FOV 7.4 arcmin

Bolometers optics: Current Vs Proposed

Top view at 0 degree elevation angle

Blue rays = (+FOV/2;0), Green rays = (0;+FOV/2), Red rays = (-FOV/2;0), Yellow rays = (0;-FOV/2)



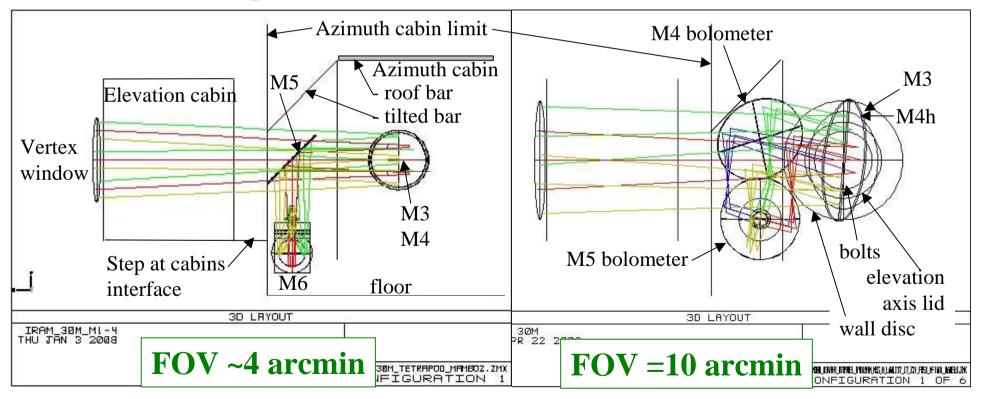
Bolometers optics: current vs proposed

Profile view at 0 degree elevation angle

Blue rays = (+FOV/2;0), Green rays = (0;+FOV/2), Red rays = (-FOV/2;0), Yellow rays = (0;-FOV/2)

Current optics

Proposed optics

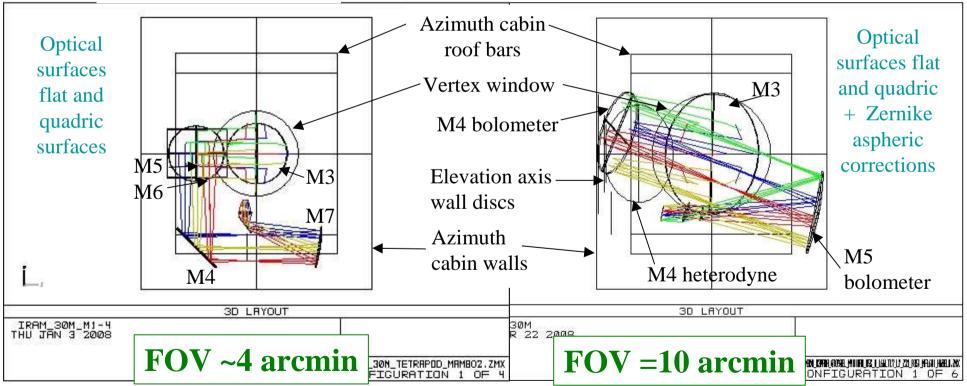


Bolometers optics: current vs proposed

Back view at 0 degree elevation angle

Blue rays = (+FOV/2;0), Green rays = (0;+FOV/2), Red rays = (-FOV/2;0), Yellow rays = (0;-FOV/2)

Current optics Proposed optics



Through focus spot diagram, bolometers

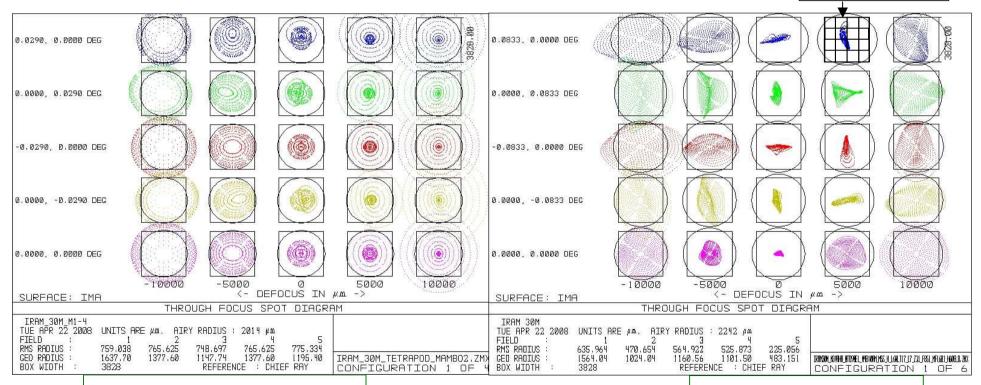
 λ =0.87mm Δ foc=5cm circle = Airy disc

Blue = (+FOV/2;0), Green = (0;+FOV/2), Red = (-FOV/2;0), Yellow = (0;-FOV/2), Magenta = (0;0)

Current optics (MAMBO 2)

Proposed optics

 4×4 pixels to sample HPBW



FOV 3.5 arcmin

PSF = Airy * Aberration

FOV 10 arcmin

M2 shift = 0.9 mm

M2 shift = 0 mm. Acceptable M2 shift = ± 0.8 mm $\rightarrow \Delta F \sim 15$ mm

Through focus spot diagram, bolometers

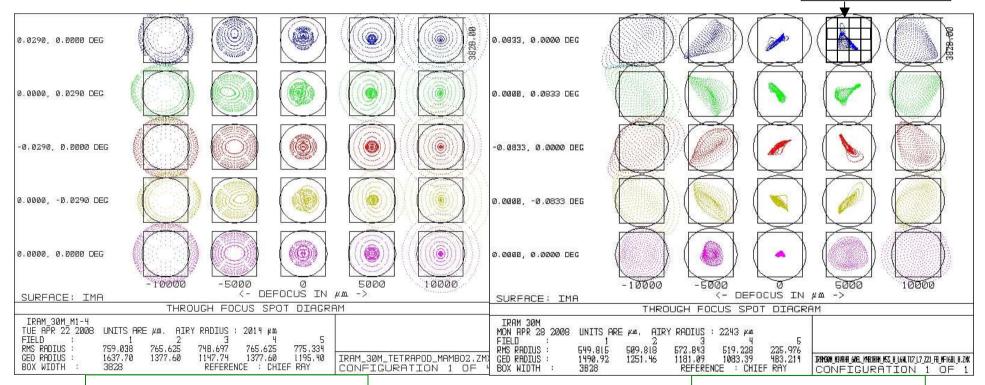
 λ =0.87mm Δ foc=5cm circle = Airy disc

Blue = (+FOV/2;0), Green = (0;+FOV/2), Red = (-FOV/2;0), Yellow = (0;-FOV/2), Magenta = (0;0)

Current optics (MAMBO 2)

Proposed optics

 4×4 pixels to sample HPBW



FOV 3.5 arcmin

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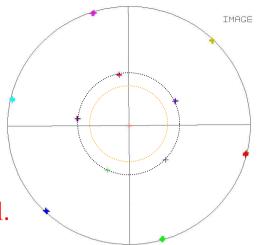
FOV 10 arcmin

M2 shift = 0.9 mm

M2 shift = 0 mm. Acceptable M2 shift = ± 0.8 mm $\rightarrow \Delta F \sim 15$ mm

Conclusion

- Heterodyne optics ready for realization phase.
- Bolometer optics need refinement, but is ready for approval.
- FOV significantly increased while keeping everything in the receiver cabin → efficient, cheap and secured solution.
- New M3 must be mounted on 2 rotating axes (its own azimuth and elevation)
 → electronics and software control, laser alignment.
- M4h must be mounted on translation rail.
- M4b, M5b, L6 and L7 have curved surfaces with complex aspheric corrections.
- To do: Solid Works; M3 and M4h motorized mounts; mechanical structure & support; laser system; electronics; control software; buy raw material; chopper replacement; machining; mounting.
- Estimated budget ~ 150-200 keuros.
- Estimated timing \sim if design approval in may \rightarrow ready for winter 2009.

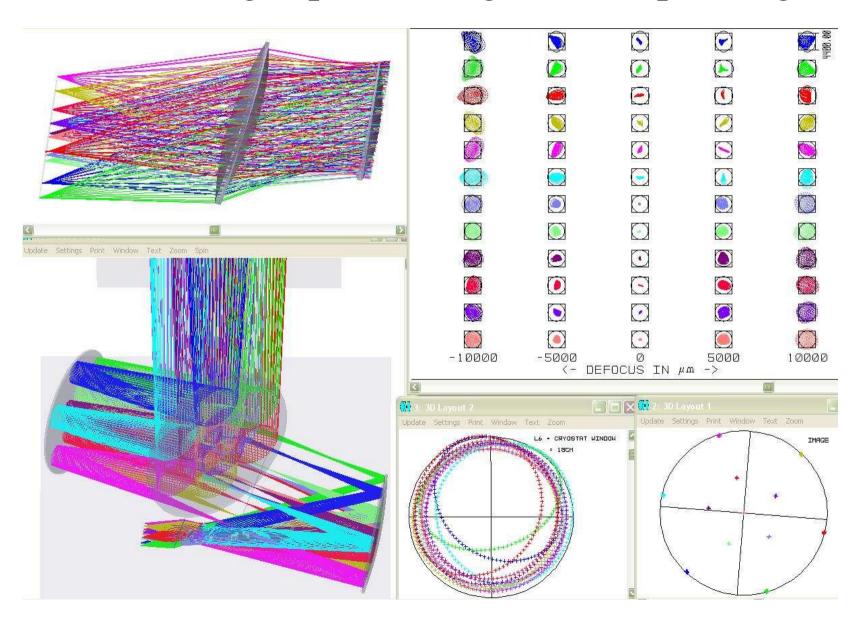


Extra slides

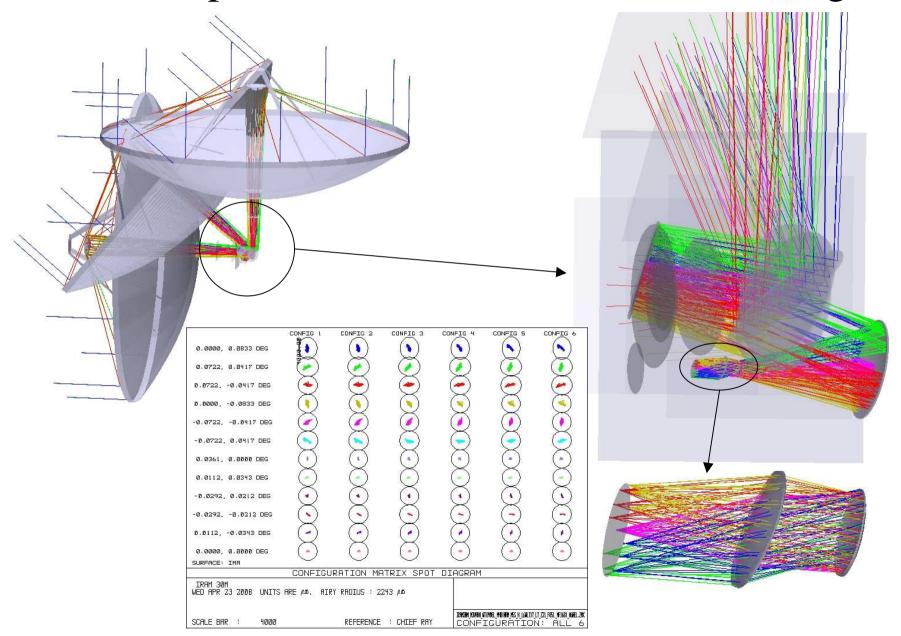
Short chronology of the study

- Late 90s: Astrophysics and technology → large Fields Of View (FOV).
- 2003-2006: Early concepts to increase the 30m FOV (S.Navarro) → new optics in receiver cabin, elements in main dish (M1) structure, new subreflector (M2).
- Fall 06: Optical software, current system in Optalix and **Zemax**, FOV study.
- May 07: 1st proposition for a new optical design, all in "receiver cabin" with a non-Nasmyth motorized M3 → 14.5' for bolos @ low cost.
- Jan $08:3^{rd}$ proposition refining specifications \rightarrow 11.4' for bolo, 7.4' for hetero.
- Feb 08: start optimization of designs based on 3rd proposition.
- Apr 08 : 1 design meets specifications $\rightarrow 10$ ' bolo, 7.4' hetero.
- June 08: start realization phase if proposed design is approved.
- Winter 09: new optics in the 30m receiver cabin.

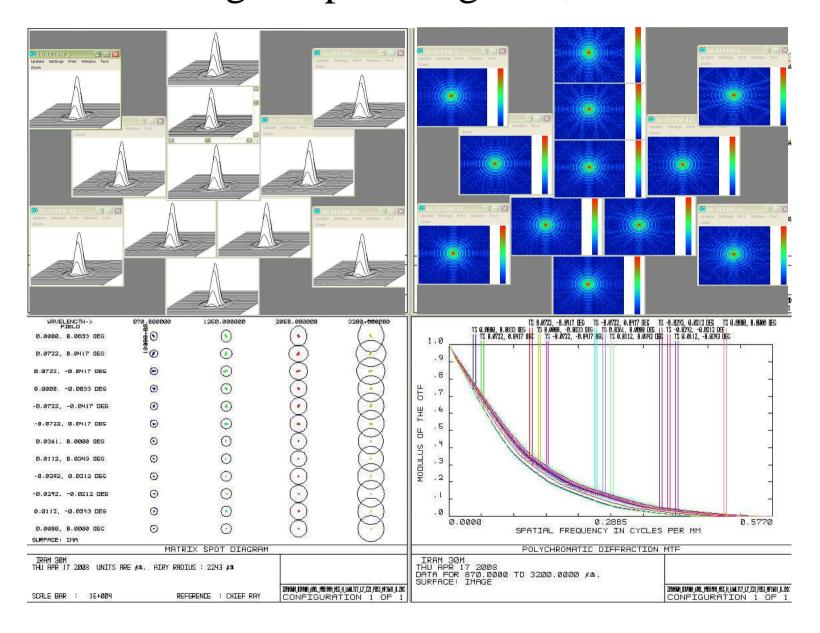
New bolo optics: multi fields shaded model, cryostat window, image spots,through-focus spot diagram



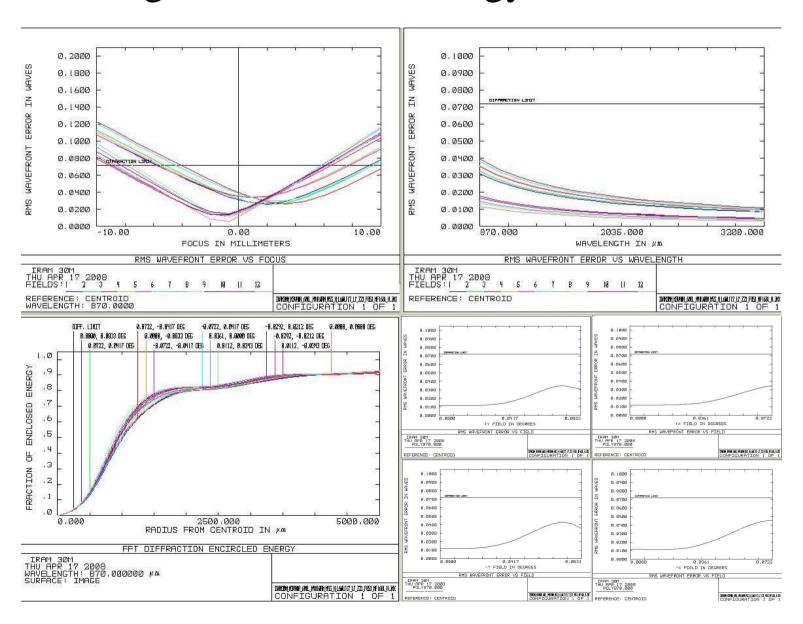
New bolo optics: behaviour with elevation change



New bolo optics: FFT PSF (linear and log), Wavelengths spots diagrams, FFT MTF



New bolo optics: RMS vs Focus, RMS vs wavelengths, Encircled energy, RMS vs Fields



Project planning

