

Trouble Shooting Guide

IRAM Plateau de Bure Interferometer

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Document probably older than you think

Version 2.0

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This document gives some information about troubleshooting at the IRAM Plateau de Bure interferometer.

Related information is available in:

- IRAM Plateau de Bure Interferometer: Foreign Commands
- IRAM Plateau de Bure Interferometer: OBS Users Guide

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1 Description

The interferometer consists of:

- Five antennas, each controlled by a VME microprocessor (the *POINTING* micro).
- One off-axis optical telescope per antenna, for pointing,
- 2 (4-6 on the long term, 2 simultaneous IF) receivers per antenna, controlled by the *RECEIVER* micro.
- The *PHASER* micro, which controls a 12-channel continuum detector, two HP-synthesizers for the LO frequencies, the phases and rates.
- The *CLOCK* micro, which controls the time distribution and also handles the meteo station.
- A 6-unit purpose spectral correlator. The digital part of each unit is divided in two VME crates, named the *MASTER* and the *SATELLITE*, which are linked by the “GigaLink”.
- A HP-J200 workstation named BURE1 for real-time command and acquisition,
- An HP-J200 workstation named BURE2 for data reduction, sharing NFS disks with the acquisition computer BURE1.
- A dedicated Ethernet link between BURE1, the *PHASER* and the correlator micros.
- A general Ethernet link between BURE1, the *CLOCK*, the antennas (*POINTING* and *RECEIVER*), BURE2 and all the other terminals/computers on the site.
- Many cables : low and high quality for the IF transmission, twisted pairs for specific signals, etc...

The instrument may be used in several basic modes: **OPTICAL** pointing, **INTERFEROMETER** observing, or **TEST** mode. In addition, within the OBS program, there is a **CONFIGURE** mode, which is used to specify and modify the array configuration parameters.

Any part of the instrument may fail, in any operating mode. The purpose of this guide is to pinpoint the most frequent failures, their effects and the remedies. It is assumed the reader has good knowledge of the “Users Guide”.

2 The Real Time system BURE1

Before proceeding to the main topic, a detailed description of the software is required.

2.1 The Tasks and Programs

The software is organised in two basic blocks:

- Real-time tasks that monitor the antenna and receivers:
 - **INTERP**: this task dialog with the antenna microprocessors every second, and occasionally send command to them.
 - **FLAG1S**: this task is a time checker. It is activated every second through a dialog with the Clock microprocessor. It also handles the meteo parameters.

- **ASTRJ** : this task does the astronomical computations to prepare the input to **INTERP**. It is activated every time a new source is requested.
- Tasks that control and perform the acquisition:
 - **CORREL**: this task controls the correlator data acquisition.
 - **CORREL_SPECTRA**: this task reads the data from the correlator micro when acquisition is finished.
 - **OBS** : High level observing program, with integrated observing procedures. Only one occurrence of **OBS** can be running on **BURE1**.
 - **RDI** : interferometric data acquisition program.
- Control and display tasks:
 - **XAFF** : perform various display tasks, including computation of the running amplitudes and phases.
 - **STSA** : this program is used to display the antenna parameters related to the pointing.
 - **STSH** : this program is used to display antenna parameters related to “survival” (de-icing, etc...).

The **OBS** program is intended to provide complete normal operation of the instrument. Accordingly, **OBS** assumes it has complete control over the system.

2.2 Commons

All real-time tasks interact through global commons:

- **GENERAL** is for general parameters,
- **ANTENNA** for antenna related parameters,
- **RECEIVER** for receiver related parameters,
- **ACQUIS** for continuum detector and correlator parameter and results,
- **OBSRED** and **ACTIVE** are shared between **OBS** and the acquisition program **RDI**.

A set of semaphores are used for synchronisation.

- **S_ANT** (**ANTENNA** common locked) (**CLEARED**)
This semaphore is blocked (set) whenever a task uses the antenna common and released (cleared) when the operation is finished. The next task requesting the common can grab it, and so on...
- **S_GENERAL** (**GENERAL** common locked) (**CLEARED**)
This semaphore is used to lock/unlock the general common.
- **S_ACQUIS** (**ACQUISITION** common locked) (**CLEARED**)
This semaphore is used to lock/unlock the acquisition common.

This scheme is used to avoid conflicting actions from several tasks.

2.3 Synchronisation

Flags are used for inter-process synchronisation, or to request some specific actions.

- ASTRO (Astronomical Computation requested) (CLEARED)
This flag is set by OBS when changing source. It is expected and cleared by ASTRJ when relevant computations have been done.
- TCPIP (Dialog with antenna micros) (CLEARED)
This flag is set by FLAG1S every second. It is expected and cleared by INTERP, which reads information from the antenna micros on such occasions.
- TRACK Tracking (SET)
This flag indicate the Antennas *and* subreflectors are in position and tracking. It is set and cleared by INTERP. It is expected by CORREL to start data acquisition.
- UT (UT time change) (CLEARED)
This flag indicate the UT time has changed. It is set by FLAG1S and expected and cleared by CORREL.
- COR (CORrelator acquisition required) (CLEARED)
This flag is set by OBS when an acquisition is requested. It is expected and cleared by CORREL.
- SUP (Interferometer setup done) (CLEARED)
This flag is set by task CORREL whenever the parameters of an acquisition are ready. It is expected and cleared by RDI.
- DAT (Interferometer data ready) (CLEARED)
This flag is set by task CORREL_SPECTRA whenever new data is available from the correlators. It is expected and cleared by RDI.
- SPECTRE (Correlator data ready) (CLEARED)
This flag is set by CORREL when an acquisition finished. It is expected and cleared by CORREL_SPECTRA which reads the data from the correlators and set flags DAT when done.
- ALARM (Alarm) (CLEARED)
This flag may be set by some program. It signals a problem...
- STARTED (Acquisition started) (CLEARED)
This flag is set by CORREL when the acquisition is running. It is expected and cleared by RDI.
- RED (RDI ready) (SET)
This flag is set by RDI when it is ready. It is expected (and later cleared) by OBS.
- CONTROL C (^C pressed) (CLEARED)
Set when ^C is pressed in OBS.

2.4 Configuration and Initialisation Files.

The “hardware” configuration of the interferometer is listed in several files:

- **INTER_BASE:CONFIG.DAT**
This file indicates some basic array parameters, specially the time corrections. It should never be changed by operators or astronomers.
- **INTER_BASE:GENERAL.ANk**
These files contain antenna dependant parameters, such as pointing constants, focus and homology parameters. The parameters change only when the antenna is repaired or modified.
- **INTER_BASE:Tij.ANk**
These files contain parameters for antenna k on station Tij (e.g. W00, not W0): IAZ, MVE, MVN, position errors dX,dY,dZ and delay offset. They have to be updated each time the antenna is set on station.
- **INTER_BASE:START.OBS**
This procedure indicates on which stations the antennas are currently located, and to which correlator entries they are connected. It also indicates which is the antenna connected to the single-dish backends.

A special language in OBS has been implemented to allow modifications of the array configuration parameters: language SET\, which is available only in the CONFIGURE mode. These files should never be modified by a text editor.

The acquisition programs RED and RDI write the data on files named INTER_DATA:Date.BUR and INTER_DATA:Date.IPB respectively, where Date is the current date in the form DD-mmm-YYYY. Three log files are created, Date.LOG-OBS by OBS Date.LOG-RED by RED and Date.LOG-RDI by RDI, in directory INTER.LOG.

3 Diagnostic Tools

3.1 STSA

STSA display the antenna coordinates and a summary of the interferometer status.

3.2 FLAG

FLAG is a small tool to display the running status of the event flags. It is able to see flag changes, provided they are not too fast.

3.3 WHY

The WHY command is the major tool for trouble shooting. It performs several consistency checks of the interferometer state, such as scanning through the list of “tasks” (e.g. INTERP) and “programs” (e.g. RDI) to see if any of them is missing.

3.4 DMP and READ_ACQUIS

DMP dumps parts of the general and/or antenna commons. READ_ACQUIS dumps the acquisition common.

4 Programs on the various microprocessor

4.1 The *POINTING* micro

It may be necessary to log on the *POINTING* micro for checks in case of anomalous behaviour.

The normal state can be checked by typing `procs -e` to check the running processes. It should say:

```
ant51_s: procs -e
  Id PId Grp.Usr  Prior  MemSiz Sig S    CPU Time   Age Module & I/O
  2   0   0.0    128    4.75k  0 w      0.00 159:19 sysgo <>>>term
  3   0   0.0    128    2.00k  0 s     37:20.78 159:19 ifman
  4   0   0.0    128   20.25k  0 s     2:32.27 159:19 routed <>>>nil
  5   0   0.0    128    2.00k  0 a     2:17.03 159:19 sockman
  6   2   0.0    128    6.75k  0 w      0.00 159:19 shell <>>>term
  7   6   0.0    128    6.75k  0 w      0.13 159:19 shell <dd >>>term
  8   0   0.0    128   62.75k  0 e     29.00 159:19 nfsc <>>>term
  9   7   0.0    128   12.00k  0 e      0.01 159:19 ftpd <>>>nil
 10   7   0.0    128   12.00k  0 e      0.44 159:19 telnetd <>>>nil
 11   7   0.0    128   15.50k  0 s      0.03 159:19 tsmon <>>>term
 12  13   2.2    128    6.75k  0 e      0.16 75:15 shell <>>>pks00
 13   0   0.0    128   22.00k  0 e      0.25 75:15 telnetdc <pks00
 14   0   0.0    128   11.25k  0 e      1.53 159:19 rmshd <dd >pipe >>nil
 15   0   0.0    128    9.50k  0 e 10:37:06.41 159:19 ev_it1s <dd >>>nil
 16   0   0.0    128   11.25k  0 e     26.77 159:19 ev_itsync <dd >>>term
 17   0   0.0    128   11.25k  0 e      0.02 159:19 ev_itincr <dd >>>term
 18   0   0.0    128   11.25k  0 e  1:27:55.70 159:19 tcpip <dd >>>nil
 19   0   0.0    128   11.25k  0 s  1:25:13.52 159:19 subxmit <>>>nil
 20  21   0.0    128    6.75k  0 w      0.18  0:00 shell <>>>pks01
 21   0   0.0    128   22.00k  0 a      0.18  0:00 telnetdc <pks01
 22  20   0.0    128   18.25k  0 *      0.36  0:00 procs <>>>pks01
```

Programs `ev_it1s`, `ev_itsync`, `ev_itincr` (the time keepers), `tcpip` (which handles communications with BURE1), `subxmit` (which communicates with the *RECEIVER* micro program `subrecv` to control the subreflector), and `rmshd` (which support the `rmsh` commands from BURE1) should all be active.

Program `user` can display all the status bits of the antenna. Program `UT` displays the running UT and LST times. Program `set_time` can be used to re-synchronize the micro and reset the UT time. LST will become good again only after a command has been sent by BURE1. Program `incr` can be used to re-initialize the encoders/subreflector. Program `dmp` dumps the antenna common.

Synchronisation problems may require to have a look at the “history” of the synchro errors. They are logged in files named `sync.ant11`, `sync.ant21`, etc.... These files should be small. To check their size, use:

```
ant51_s: chd /dd/ANTENNA
ant51_s: dir -e sync.*
  Owner      Last modified  Attributes Sector Bytecount Name
  -----
  0.0        96/07/16 0314  -----wr    1B51      150 sync.ant11
```

```

0.0      96/07/16 0230  -----wr      1B50      125 sync.ant31
0.0      96/07/16 0230  -----wr      1BC0       50 sync.ant41
0.0      96/07/16 0230  -----wr      1B52       50 sync.ant51

```

The size (Bytecount) should be less than about 2000 bytes. Otherwise, too many timing errors have appeared: check the TU01 time bus. The sync.ant*i*1 files contain the date and time of the error:

```

ant51_s: list sync.11
Tue Jul 16 09:31:42 1996
Tue Jul 16 09:31:43 1996
Tue Jul 16 10:15:27 1996
Tue Jul 16 10:15:35 1996
Tue Jul 16 10:15:41 1996
Tue Jul 16 10:15:47 1996

```

If the file size keep increasing, the antenna are no longer properly synchronized. Use command `set.time` to re-synchronize them and reset the UT time. If the files get too large (Bytecount > 10000), delete them using command

```
ant51_s: del sync.ant*
```

4.2 The *RECEIVER* micro

This micro controls the receivers and the subreflector of the antenna. The following programs should be running:

```

ant12_o: procs -e
  Id Pid Grp.Usr  Prior  MemSiz Sig S    CPU Time   Age Module & I/O
  2   0   0.0    128    4.75k  0 w      0.00 181:49 sysgo <>>>term
  3   0   0.0    128    2.00k  0 e    2:26:25.17 181:49 ifman
  4   0   0.0    128   20.25k  0 s      3:43.81 181:49 routed <>>>nil
  5   0   0.0    128    2.00k  0 s      49.74 181:49 sockman
  6   2   0.0    128    6.75k  0 w      0.00 181:49 shell <>>>term
  7   6   0.0    128    6.75k  0 w      0.16 181:49 shell <dd >>>term
  8   0   0.0    128   62.75k  0 e      3.35 181:49 nfsc <>>>term
  9   7   0.0    128   12.00k  0 e      0.01 181:49 ftpd <>>>nil
 10   7   0.0    128   12.00k  0 e      0.11 181:49 telnetd <>>>nil
 11   7   0.0    128   15.50k  0 w      0.04 181:48 tsmon <>>>term
 12  17   0.0    128    7.00k  0 e     2:23.16 12:59 rserverc <socket >>>nil
 13  17   0.0    128    7.00k  0 e      5.94  3:01 rserverc <socket >>>nil
 14   0   0.0    128    5.00k  0 s     43.21 181:48 sts <>>>nil
 15   0   0.0    128    5.00k  0 a     11.22 181:48 subloo <>>>nil
 16   0   0.0    128   11.25k  0 e    57:59.04 181:48 subrecv <>>>nil
 17   0   0.0    128   11.25k  0 e     12.72 181:48 rserver <socket >>>nil
 18   0   0.0    128   11.25k  0 e      0.01 181:48 rmshd <dd >pipe >>nil
 19  20   2.2    128   16.00k  0 a    26:19.50 14:33 user <>>>pks00
 20  21   2.2    128    6.75k  0 w      1.29 167:41 shell <>>>pks00
 21   0   0.0    128   22.00k  0 e    27:29.95 167:41 telnetdc <pks00
 22  24   2.2    128    6.75k  0 w      0.26  0:00 shell <>>>pks01

```



```

23 11 0.0 128 14.75k 0 s 0.09 166:20 login <>>>term
24 0 0.0 128 22.00k 0 e 0.19 0:00 telnetdc <pks01
25 22 2.2 128 18.25k 0 * 0.54 0:00 procs <>>>pks01

```

Programs **sts** (receiver monitoring), **subloo** and **subrecv** (subreflector control), **rmshd** (support for the **rmsb** commands from BURE1) should all be active.

Program **user** can display all the status of the receiver.

4.3 The *CLOCK* micro

The following programs should be running on that micro:

```
clock: procs -e
```

| Id | PI | Grp. | Usr | Prior | MemSiz | Sig | S | CPU | Time | Age | Module & I/O |
|----|----|------|-----|---------|--------|-----|---|----------|--------|----------|--------------|
| 2 | 0 | 0.0 | 128 | 7.75k | 0 | w | | 0.04 | 143:20 | sysgo | <>>>term |
| 6 | 0 | 0.0 | 128 | 18.75k | 0 | s | | 1:27.51 | 143:20 | routed | <>>>nil |
| 7 | 0 | 0.0 | 128 | 2.00k | 0 | a | | 9:39.09 | 143:20 | ifman | |
| 8 | 0 | 0.0 | 128 | 2.00k | 0 | s | | 0.01 | 143:20 | sockman | |
| 11 | 0 | 0.0 | 128 | 105.75k | 0 | e | | 0.24 | 143:20 | nfsc | <>>>term |
| 12 | 2 | 0.0 | 128 | 8.25k | 0 | w | | 0.00 | 143:20 | shell | <>>>term |
| 13 | 12 | 0.0 | 128 | 8.25k | 0 | w | | 0.12 | 143:20 | shell | <dd>>>term |
| 18 | 13 | 0.0 | 128 | 20.50k | 0 | e | | 0.01 | 143:20 | ftpd | <>>>nil |
| 19 | 13 | 0.0 | 128 | 20.50k | 0 | e | | 0.04 | 143:20 | telnetd | <>>>nil |
| 35 | 0 | 0.0 | 128 | 14.25k | 0 | e | | 43:48.04 | 143:20 | ev_it1s1 | <dd>>>nil |
| 39 | 0 | 0.0 | 128 | 10.25k | 0 | s | | 0.00 | 143:20 | meteo | <dd>>>nil |
| 41 | 0 | 0.0 | 128 | 15.00k | 0 | e | | 0.21 | 143:20 | server | <dd>>>nil |
| 43 | 13 | 0.0 | 128 | 23.75k | 0 | s | | 0.04 | 143:20 | tsmon | <dd>>>term |
| 45 | 0 | 0.0 | 128 | 30.75k | 0 | e | | 0.13 | 0:00 | telnetdc | <pks00 |
| 46 | 45 | 0.0 | 128 | 8.25k | 0 | w | | 0.19 | 0:00 | shell | <>>>pks00 |
| 53 | 46 | 0.0 | 128 | 26.75k | 0 | * | | 0.32 | 0:00 | procs | <>>>pks00 |

Programs **ev_it1s1**, **server** (the time servers), and **meteo** (which reads the meteo station) should be running.

4.4 the *PHASER* micro

The following programs should be running on that micro:

```
$ procs -e
```

| Id | PI | Grp. | Usr | Prior | MemSiz | Sig | S | CPU | Time | Age | Module & I/O |
|----|----|------|-----|--------|--------|-----|---|---------|-------|---------|--------------|
| 2 | 0 | 0.0 | 128 | 9.50k | 0 | w | | 0.00 | 11:26 | sysgo | <>>>term |
| 3 | 2 | 0.0 | 128 | 6.75k | 0 | w | | 0.00 | 11:26 | shell | <>>>term |
| 4 | 0 | 0.0 | 128 | 20.25k | 0 | s | | 10.53 | 11:26 | routed | <>>>nil |
| 5 | 0 | 0.0 | 128 | 2.00k | 0 | e | | 1:25.73 | 11:26 | ifman | |
| 6 | 0 | 0.0 | 128 | 2.00k | 0 | s | | 3.25 | 11:26 | sockman | |
| 7 | 3 | 0.0 | 128 | 6.75k | 0 | w | | 0.10 | 11:26 | shell | <dd>>>term |
| 8 | 0 | 0.0 | 128 | 62.75k | 0 | e | | 0.28 | 11:26 | nfsc | <>>>term |
| 9 | 7 | 0.0 | 128 | 12.00k | 0 | e | | 0.00 | 11:26 | ftpd | <>>>nil |
| 10 | 7 | 0.0 | 128 | 12.00k | 0 | e | | 0.03 | 11:26 | telnetd | <>>>nil |
| 11 | 12 | 0.0 | 128 | 5.25k | 0 | s | | 8:47.09 | 11:26 | rotator | <dd>>>nil |

```

12  0  0.0    128   21.25k  0 e    10:37.16 11:26 server <dd >>>nil
13 12  0.0    128    0.00k  0 -          0.00 11:26 <none>
14 12  0.0    128   11.50k  0 s          0.03 11:26 hp_synt <dd >>>nil
15 12  0.0    128    5.00k  0 s          0.00 11:26 noise <dd >>>nil
16 12  0.0    128    5.00k  0 s          0.00 11:26 watchdog <dd >>>nil
17  7  0.0    128   15.50k  0 s          0.01 11:26 tsmon <dd >>>term
18 19  0.0    128    6.75k  0 w          0.46  0:00 shell <>>>pks00
19  0  0.0    128   22.00k  0 a          0.19  0:00 telnetdc <pks00
20 18  0.0    128   18.25k  0 *          0.30  0:00 procs <>>>pks00

```

Programs *rotator* (phase rotator control), *hp_synt* (frequency synthesizer control), *noise* (noise source commutation), *watchdog* (radio alarm), and *server* (total power output) should be running.

4.5 The *MASTER* and *SATELLITE* micros

corl01: procs -e

| Id | PId | Grp. | Usr | Prior | MemSiz | Sig | S | CPU | Time | Age | Module & I/O |
|----|-----|------|-----|-------|---------|-----|---|------|------|----------|--------------|
| 2 | 0 | 0.0 | | 128 | 7.75k | 0 | w | 0.01 | 1:37 | sysgo | <>>>term |
| 4 | 64 | 0.0 | | 128 | 75.25k | 0 | s | 0.13 | 0:04 | calcul | <>>>pks00 |
| 5 | 64 | 0.0 | | 128 | 28.50k | 0 | s | 0.00 | 0:04 | setIF | <>>>pks00 |
| 6 | 0 | 0.0 | | 128 | 18.75k | 0 | s | 0.02 | 1:37 | routed | <>>>nil |
| 7 | 0 | 0.0 | | 128 | 2.00k | 0 | e | 0.40 | 1:37 | ifman | |
| 8 | 0 | 0.0 | | 128 | 2.00k | 0 | s | 0.00 | 1:37 | sockman | |
| 9 | 64 | 0.0 | | 128 | 34.25k | 0 | e | 0.01 | 0:04 | spectra | <>>>pks00 |
| 11 | 0 | 0.0 | | 128 | 105.75k | 0 | e | 0.19 | 1:37 | nfsc | <>>>term |
| 12 | 2 | 0.0 | | 128 | 8.25k | 0 | w | 0.00 | 1:37 | shell | <>>>term |
| 13 | 12 | 0.0 | | 128 | 8.25k | 0 | w | 0.02 | 1:37 | shell | <dd >>>term |
| 15 | 64 | 0.0 | | 128 | 28.00k | 0 | s | 0.00 | 0:04 | tweak | <>>>pks00 |
| 17 | 0 | 0.0 | | 128 | 30.75k | 0 | a | 0.03 | 0:00 | telnetdc | <pks01 |
| 18 | 13 | 0.0 | | 128 | 20.50k | 0 | e | 0.00 | 1:37 | ftpd | <>>>nil |
| 19 | 13 | 0.0 | | 128 | 20.50k | 0 | e | 0.01 | 1:37 | telnetd | <>>>nil |
| 20 | 17 | 0.0 | | 128 | 8.25k | 0 | w | 0.02 | 0:00 | shell | <>>>pks01 |
| 27 | 13 | 0.0 | | 128 | 23.75k | 0 | s | 0.01 | 1:37 | tsmon | <dd >>>term |
| 28 | 20 | 0.0 | | 128 | 26.75k | 0 | * | 0.08 | 0:00 | procs | <>>>pks01 |
| 29 | 0 | 0.0 | | 128 | 30.75k | 0 | e | 0.12 | 1:37 | telnetdc | <pks00 |
| 30 | 29 | 0.0 | | 128 | 8.25k | 0 | w | 0.12 | 1:37 | shell | <>>>pks00 |
| 64 | 30 | 0.0 | | 128 | 211.50k | 0 | e | 0.12 | 0:04 | correl | <>>>pks00 |

Programs *calcul*, *setIF* (IF processor setting), *spectra* *correl* and *tweak* should be running on the *MASTER*. The *SATELLITE* is similar, except that program *setIF* does not run.

5 “Normal State” Definitions

This section defines a terminology used to refer to “normal states” of the array afterwards.

- Single-Dish Continuum OK

This means a continuum point source can be detected (in total power mode) with the

one dish antenna. It implies that all the antenna control tasks work, that the pointing parameters are reasonably accurate for that antenna.

- Single-Dish OK
This means a (standard) line source can be detected in ONOFF with one antenna. In addition to the previous state, it also implies that the receiver is tuned to the right frequency.
- Multi-Dish continuum OK
This means a continuum point source can be detected (in total power mode) with the continuum dish detectors on all antennas. It implies the antenna control taks work for all antennas.
- Multi-Dish OK
This means a (standard) line source can be detected on all antennas with the OBS ONOFF procedure. In addition to the previous state, it also implies that all receivers are tuned to the right frequency.

The last stage (which includes all the previous ones) is necessary for interferometry to work, but it may not be sufficient.

6 Standard Check List

To avoid further potential problems, the following procedure should be followed as closely as possible to get started.

- Start OBS, select the program source and the program frequency, then type LOAD and immediately after MICRO. This is normally done by the recommended PR:Name.OBS setup procedure, for project “Name”.
- Tune the receivers.
- In parallel, you may initialize the antennas and subreflectors if not done, open the central hub, etc... When antennas have been initialized, select a strong continuum source to check pointing, type LOAD.
- As soon as receiver are tuned, use a CALIBRATE procedure (in INTER mode). All receiver temperatures should be reasonable.
- Make an BANDPASS procedure to calibrate the IF passband characteristic. Look at the result using CLIC. This checks the spectral correlator up to a certain point. If anything is unusual, notify the maintenance staff.
- Select a strong line source (for that frequency, see catalog of strong line sources), and use an ONOFF procedure. Line should be detected in all antennas.
- Select a strong continuum point source to determine delays on all antennas if unknown.
- Make a POINT on that source. All antennas should be pointed.
- Eventually send the phase calibrator used for your program source, and start interferometry. Phases on AFF should be constant.

7 Trouble Shooting Receipes

In many of these cases, the WHY command may be sufficient to pinpoint the error. WHY is not allmighty, however, and a good understanding of the common mistakes and failures help.

7.1 Nothing Happens

Scans won't start, or LST does not run, etc...

- A major real-time program probably died. Use command WHY, it will tell you which. During working hours, try to call S.Guilloteau. Otherwise, use command SET\RESTART in OBSto restart the missing program, and notify S.Guilloteau.
- If no major program is missing, and LST does not run, check the CLOCK micro: it may be necessary to reboot it.

7.2 Antenna won't move

- Emergency stop on, or antenna in local. Use STSA page to check.
- The antenna is not in the default "telescope" (`anttel`). Use `dmp` or WHY to check, and reload the configuration from OBS (using command SET\OBSERVE.
- Use command WHY to check whether INTERP is running.
- Door contact lost (`C_Po = 0`) in the antenna. Use program `user` in the *POINTING* micro to check.

7.3 Antenna does not reach source, but keeps trying

Check source elevation (must be > 3 and < 86 degrees) and sun distance (variable DSUN, must be > 35 degrees).

Antenna encoders (Az and/or El) not initialized.

7.4 Scan does not start

- Antenna(s) not tracking. WHY will tell you
- Subreflector(s) not ready. Check init button on STSA display. WHY will tell you.
- RDI missing. Use command WHY to check.
- CORREL missing. Use command WHY to check.
- CORREL_SPECTRA missing. Use command WHY to check.
- *PHASER* micro not properly running. Check and reboot it if needed.

7.5 Crazy calibration results

- Check that the central hub is opened (STSA)
- Check that the table moves (`user` program on *RECEIVER* micro).
- Check the receiver LO power.

7.6 No single-dish continuum data

- Check that the central hub is opened (STSA), and that the table is in position (*RECEIVER user*).
- If both are correct, it means the pointing is bad. Check the antenna time (UT program on the

POINTING micro).

- If bad, reset it using the `set_time` program on the *POINTING* micro.
- Reload the pointing constants (by a `SET\OBSERVE` command), and check the pointing.
- If still bad, reinitialize the antenna, and check the pointing.

7.7 No single-dish spectral lines

- Be sure you are observing a strong line source. Assuming single-dish continuum is working, this indicates a wrong harmonic number on receiver.

7.8 Multi-dish continuum OK, but no fringes at all on XAFF

- Could be the delay: check with CLIC whether fringes appear on the spectral correlator.
- Check phase rotator “flashing” lights.
- Check correlator power supplies.
- If problem persists, reset the *PHASER* micro.
- If problem persists, reset the correlator *MASTER* and *SATELLITES* micros.

7.9 Multi-dish continuum OK, but no fringes on one antenna on XAFF

(This means at least two bad baselines, usually...)

- Phase lock not properly closed. Look on spectrum analyser
- Bad frequency (harmonic number) on that antenna. Make a single-dish spectrum on a strong line source to check if possible.
- Retune receiver to correct harmonic number, after resetting LO2.

7.10 Unusually high Tsys on one antenna

- Check receiver physical temperature: it may need helium refilling.
- Check tuning and LO power.

7.11 Lower intensity on some baselines on XAFF display

- Bad pointing (check time), or bad focus on one antenna - bad LO power adjustment or receiver tuning on one antenna. - Strong atmospheric phase fluctuations can also produce such an effect, if the baselines are much longer than the other ones.

7.12 Intensity jump on two baselines

- Possible pointing problem. Check pointing. If jump due to pointing, reinitialize antenna (only, not subreflector), check pointing again.
 - Possible focus problem. Check focus. If jump due to focus, reinitialize subreflector separately, and check focus again.
- Report pointing and focus jump if needed.

7.13 Fringes suddenly disappear

- Use command `WHY` to check whether all programs are running.
- Possible time problem. Check the Clock micro.

- Check the Phaser micro.

7.14 Correlator subband not working on one antenna

- Can be the LO3: check the “lock” indicator.
- Can also be the filters. Check several bandwidths to disentangle between various filters. Make a BANDPASS calibration, analyse it with CLIC: check whether autocorrelation mode is OK.
- If autocorrelation not correct, sampler problem most likely.
- If OK, digital problem in the correlator board or *GigaLink*. Try resetting the micro.

If problem persists, call maintenance. In all cases notify maintenance team.

7.15 Other funny problem

Call Stephane Guilloteau, or Robert Lucas, or whoever may be “expert”. Notify Stephane Guilloteau in any of these cases. Make a dump of the commons (command DMP).

7.16 Other not funny problem

As above, but we prefer the previous ones.