























$$\sigma_K = \frac{T_{\text{sys}}}{\sqrt{2} dv \Delta t}.$$







$$\pi_{\text{sys}} = \sqrt{\pi_{\text{sys}} \pi_{\text{sys}}}$$





1992

2

100

$$\sigma_K = \frac{T_{\rm sys}}{\eta_{\rm spec} \sqrt{2} dv \Delta t}.$$





$$j_{\text{ant}}^{\text{sd}} = \frac{2k F_{\text{eff}}}{A_{\text{eff}}} ;$$







$$\sigma_{Jy} = \frac{J_{\text{ant}}^{\text{sd}} T_{\text{sys}}}{\eta_{\text{spec}} \sqrt{2} dv \Delta t}.$$

2017

$$\sqrt[n]{a_{ij}} = \sqrt[n]{a_{ji}}$$

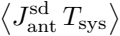


and
all

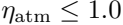
A pixelated, black and white representation of the mathematical expression $\exp(-1) \cdot \exp(2)$. The characters are rendered in a low-resolution, dithered font style. The expression consists of the word 'exp' followed by a minus sign, the number '1', a multiplication dot, the number '2', and another 'exp'. The entire image is composed of a grid of black and white pixels on a white background.



$$\sigma_{\mathrm{Jy}} = \frac{\left(J_{\mathrm{ant}}^{\mathrm{sd}} T_{\mathrm{sys}} \right)}{\eta_{\mathrm{spec}} \sqrt{n_{\mathrm{ant}} \left(n_{\mathrm{ant}} - 1 \right)} dv \Delta t},$$









$$j_{\text{ant}}^{\text{int}} = \frac{j_{\text{ant}}^{\text{sd}}}{\eta_{\text{atm}}}$$

WILLIAM

1871

1871

Q. 1. 1. 1. 1.

$$\text{rotation} = e^{-\frac{\phi^2}{2\pi m}} e^{i\pi}$$

$$\sigma_{Jy} = \frac{\langle J_{\text{ant}}^{\text{int}} T_{\text{sys}} \rangle}{\eta_{\text{spec}} \sqrt{n_{\text{ant}} (n_{\text{ant}} - 1)} dv \Delta t}.$$

$$\sigma_{Jy} = \frac{\langle J_{\text{ant}}^{\text{int}} T_{\text{sys}} \rangle}{\eta_{\text{spec}} \sqrt{n_{\text{ant}} (n_{\text{ant}} - 1)} d\nu \Delta t}, \quad \text{with} \quad J_{\text{ant}}^{\text{int}} = \frac{J_{\text{ant}}^{\text{sd}}}{\eta_{\text{atm}}} \quad \text{and} \quad \eta_{\text{atm}} = e^{-\frac{\phi_{\text{rms}}^2}{2}} \leq 1.0,$$



1000

1

1000



NEWBORN









$$j_{\text{ant}} = \frac{2k \Omega_{\text{ant}} F_{\text{eff}}}{\lambda^2} \cdot$$

QPR100

$$j_{\text{ant}}^{\text{int}} = \frac{j_{\text{ant}}^{\text{sd}}}{\eta_{\text{atm}}} = \frac{1}{\eta_{\text{atm}}} \frac{F_{\text{eff}}}{B_{\text{eff}}} \frac{2k\Omega_{\text{prim}}}{\lambda^2}.$$

QWERTY



2014

—
—

1

1000

1000

1000

$$\sqrt{\frac{\rho_{\text{syn}}}{\rho_{\text{ant}}}} = \frac{2k\Omega_{\text{syn}}}{\lambda^2} \cdot$$

$$\sigma_K = \frac{\sigma_{Jy}}{J_{\text{ant}}^{\text{syn}}} \quad \text{with} \quad J_{\text{ant}}^{\text{syn}} = \frac{2\pi k \theta_{\text{maj}} \theta_{\text{min}}}{4 \ln 2 \lambda^2},$$

$$\sigma_K = \frac{\Omega_{\text{prim}}}{\Omega_{\text{syn}}} \left\langle \frac{F_{\text{eff}} T_{\text{sys}}}{B_{\text{eff}} \eta_{\text{atm}}} \right\rangle \frac{1}{\eta_{\text{spec}} \sqrt{n_{\text{ant}} (n_{\text{ant}} - 1)} d\nu \Delta t} = \frac{\theta_{\text{prim}}^2}{\theta_{\text{maj}} \theta_{\text{min}}} \left\langle \frac{F_{\text{eff}} T_{\text{sys}}}{B_{\text{eff}} \eta_{\text{atm}}} \right\rangle \frac{1}{\eta_{\text{spec}} \sqrt{n_{\text{ant}} (n_{\text{ant}} - 1)} d\nu \Delta t},$$

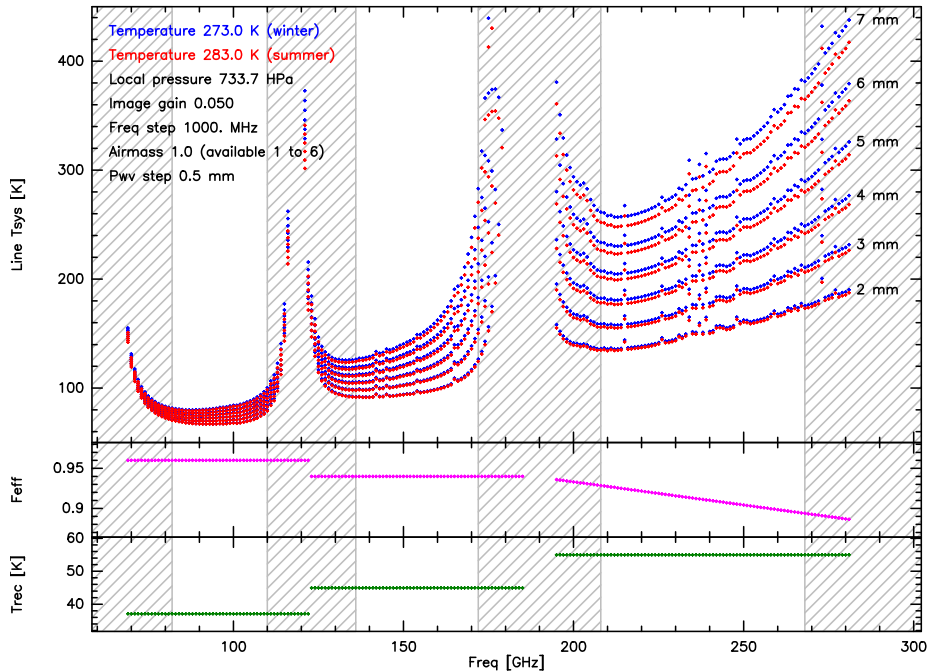
Q. 100

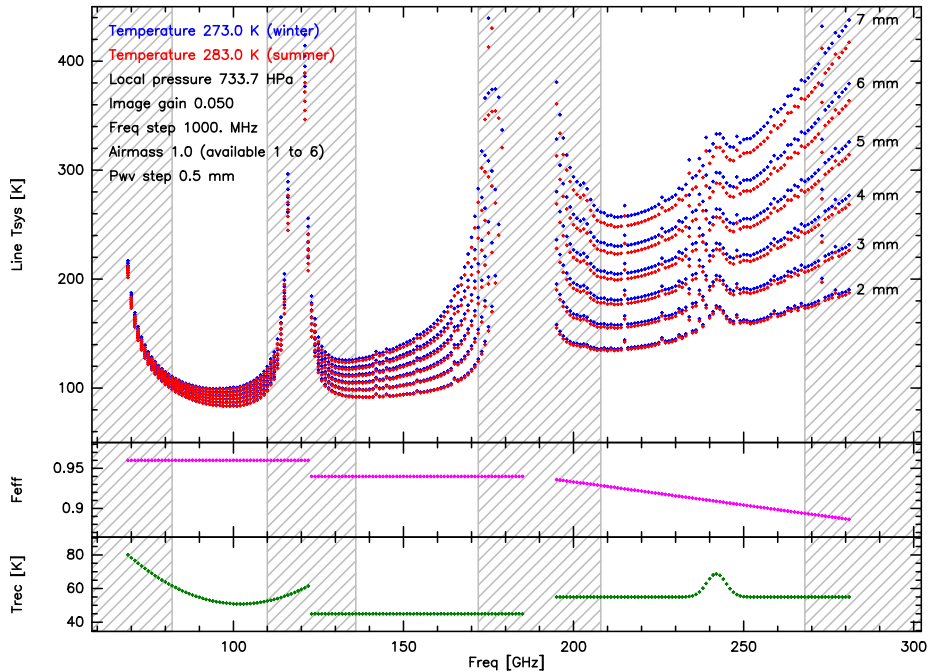


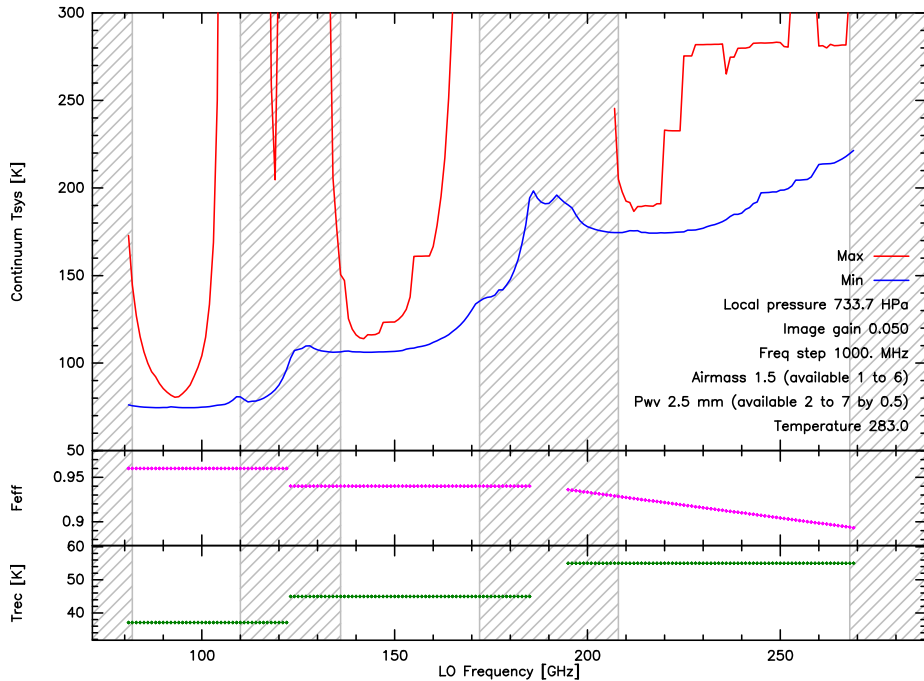


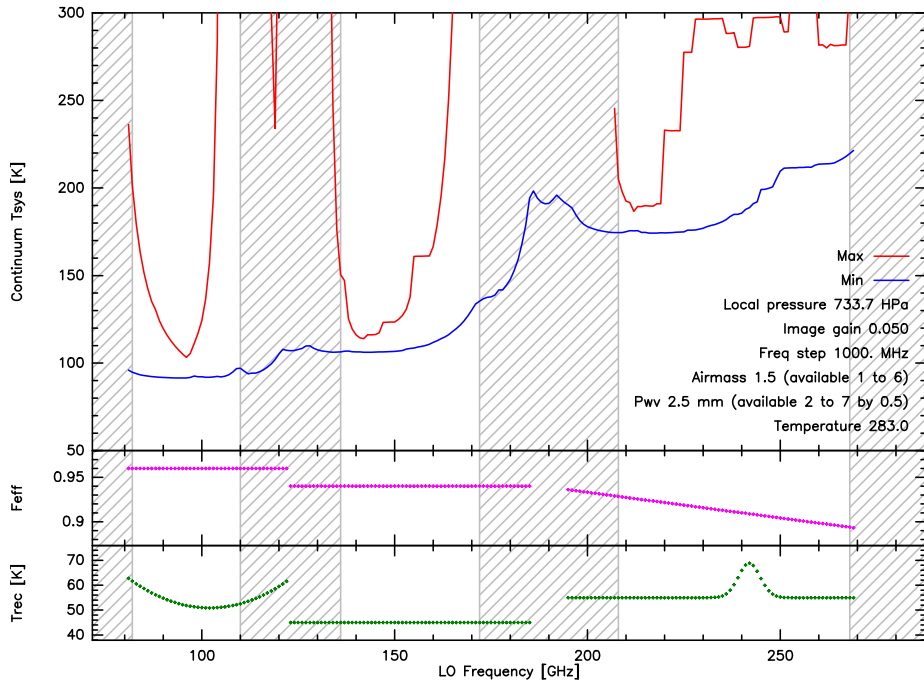
100% 24

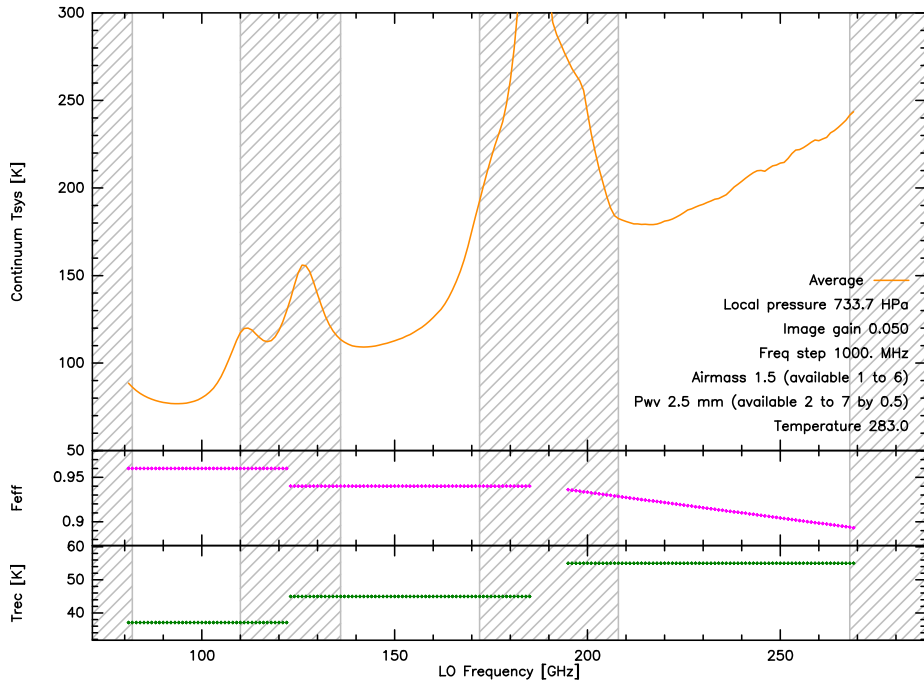


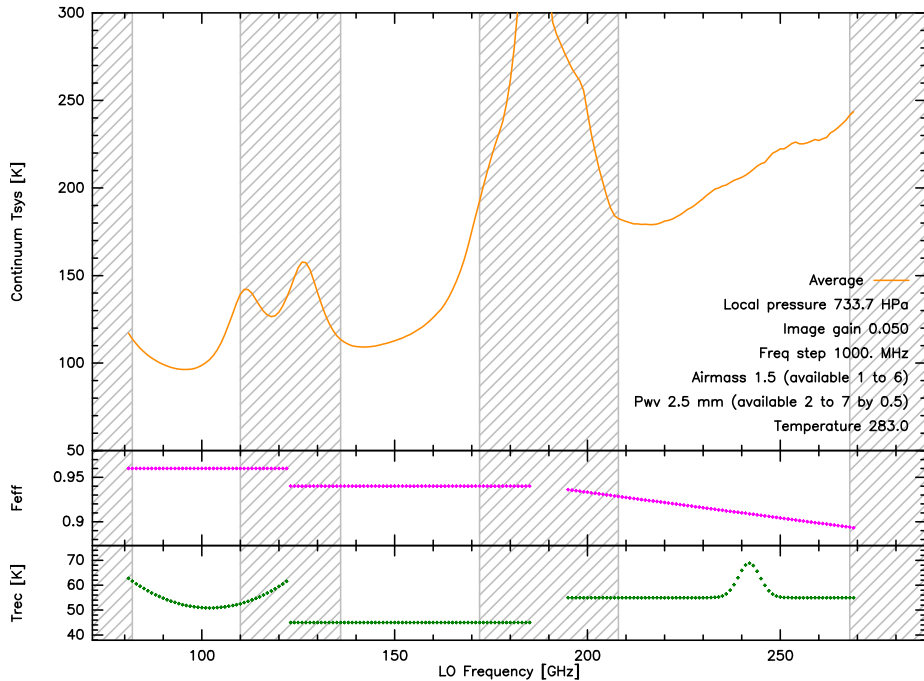












$$T_{sys} = \frac{(1 + G_{im}) \exp \{ \tau_s A \}}{F_{eff}} [F_{eff} T_{atm} (1 - \exp \{ -\tau_s A \}) + (1 - F_{eff}) T_{cab} + T_{rec}],$$





Adrianus









$$\frac{1}{\langle T_{\text{sys}} \rangle^2} = \frac{1}{N} \sum \frac{1}{T_{\text{sys}}^2} \cdot$$







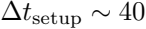
$$\sigma_{Jy} = \frac{j_{\rm ant}^{\rm int} T_{\rm sys}}{\eta_{\rm spec} \sqrt{n_{\rm ant} (n_{\rm ant} - 1)} dv n_{\rm pol} \Delta t_{\rm on}} .$$

$$\sigma_{Jy} = \frac{J_{\text{ant}}^{\text{int}} T_{\text{sys}}}{\eta_{\text{spec}} \sqrt{n_{\text{ant}} (n_{\text{ant}} - 1)} d\nu n_{\text{pol}} \Delta t_{\text{on}}} \quad \text{with} \quad J_{\text{ant}}^{\text{int}} = \frac{J_{\text{ant}}^{\text{sd}}}{\eta_{\text{atm}}} \quad \text{and} \quad \eta_{\text{atm}} = e^{-\frac{\phi_{\text{rms}}^2}{2}} \leq 1.0,$$

$$\sigma_K = \frac{\sigma_{Jy}}{J_{\text{ant}}^{\text{syn}}} \quad \text{with} \quad J_{\text{ant}}^{\text{syn}} = \frac{2\pi k \theta_{\text{maj}} \theta_{\text{min}}}{4 \ln 2 \lambda^2}.$$







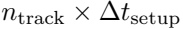


$$\Delta t_{\text{setup}} = \Delta t_{\text{setupmin}} + (n_{\text{freq}} - 1) \Delta t_{\text{setup}} / \text{freq};$$

Upland

△✱sewpriseg





100%

$$\Delta t_{obs} = \Delta t_{tel} - n_{track} \times \Delta t_{setup}.$$

$$n_{\text{track}} = \frac{\Delta t_{\text{tel}}}{\Delta t_{\text{visible}} + \Delta t_{\text{setup}}},$$

Walden

0.99

[illegible]

2019

△ + △ = △

Δt_{on}

$=$

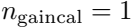
Δt_{obs}

$\times$

η_{obs}

A pixelated, grayscale image of the text "100%". The first "100%" is small and positioned on the left. To its right is a much larger, stylized "100%". The large "100%" features a thick vertical bar for the first "1", a small square for the decimal point, and a circular "0" with a thick outline. The entire image has a low-resolution, dithered appearance.





$$\eta_{\text{obs}} = \frac{1}{\Omega_{\text{obs}}} \quad \text{with} \quad \Omega_{\text{obs}} = \Omega_{\text{min}} + n_{\text{gaincal}} n_{\text{freq}} \Omega_{\text{/freq/gaincal}}, \quad \Omega_{\text{min}} = 1.3, \quad \text{and} \quad \Omega_{\text{/freq/gaincal}} = 0.3.$$



Uppercase and lowercase letters, numbers, and symbols.

100%

100%

100%

2020-2021

opinion



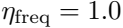
$$\eta_{\text{tot}} = \frac{\Sigma \Delta t_{\text{on}}}{\Delta t_{\text{tel}}}$$

WORLD OF

$$\sigma_{Jy} = \frac{j_{\rm ant}^{\rm int} T_{\rm sys}}{\eta_{\rm spec} \sqrt{n_{\rm ant} (n_{\rm ant} - 1)} dv n_{\rm pol} \Delta t_{\rm on}},$$

$$\Delta t_{on} = \eta_{obs} \eta_{freq} (\Delta t_{tel} - n_{track} \times \Delta t_{setup}) ,$$





A pixelated, grayscale version of the text "Wag the Dog". The letters are composed of various shades of gray and black pixels, giving it a retro, digital appearance. The text is arranged in a single line, with "Wag" followed by "the" and "Dog".





$$\sigma_{Jy} = \frac{j_{\text{ant}}^{\text{int}} T_{\text{sys}}}{\eta_{\text{spec}} \sqrt{n_{\text{ant}} (n_{\text{ant}} - 1)} dv n_{\text{pol}} \Delta t_{\text{on}}}$$

$$\Delta t_{\text{on}} = \eta_{\text{obs}} \eta_{\text{freq}} \left(\frac{\Delta t_{\text{tel}} - n_{\text{track}} \times \Delta t_{\text{setup}}}{n_{\text{sou}}} \right) .$$



$$n_{\text{beam}} = \frac{A_{\text{map}}}{A_{\text{beam}}}$$

1990



$$A_{\text{beam}} = \frac{0.8 \pi \theta_{\text{prim}}^2}{4 \ln(2)} ;$$

$$\sigma_{Jy} = \frac{j_{\text{ant}}^{\text{int}} T_{\text{sys}}}{\eta_{\text{spec}} \sqrt{n_{\text{ant}} (n_{\text{ant}} - 1)} dv n_{\text{pol}} \Delta t_{\text{on}}}$$

$$\Delta t_{\text{on}} = \eta_{\text{obs}} \eta_{\text{mos}} \left(\frac{\Delta t_{\text{tel}} - n_{\text{track}} \times \Delta t_{\text{setup}}}{n_{\text{beam}}} \right), \quad \text{and} \quad \eta_{\text{mos}} = \frac{\Delta t_{\text{point/cycle}}}{\Delta t_{\text{point/cycle}} + \Delta t_{\text{slew}}},$$

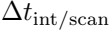
penitence

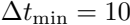
1991



$$n_{\text{point}} = n_{\text{beam}} \left(\frac{7}{4} \right)^2,$$









$$\frac{\Delta t_{\text{int}}/\text{scan}}{1\text{s}} < < \frac{6900}{\theta_{\text{alias}}/\theta_{\text{syn}}},$$

Q112

QWID

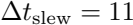
$$\Delta t_{\text{int}/\text{scan}} \leq \eta \frac{6900}{1\text{sec}} \sqrt{\frac{\theta_{\text{maj}}\theta_{\text{min}}}{A_{\text{map}}}},$$



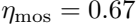




$$\leq \Delta t_{\text{int}/\text{scan}} = \min \left(45 \text{ sec}, \eta \frac{6\,900}{1 \text{ sec}} \sqrt{\frac{\theta_{\text{maj}} \theta_{\text{min}}}{A_{\text{map}}}} \right) \quad \text{with} \quad \eta = 0.5.$$



A pixelated, black and white graphic of the text "The End of the World". The text is rendered in a highly stylized, jagged, and somewhat abstract font. The letters are composed of many small, dark pixels, giving it a grainy, digital appearance. The overall shape of the text is elongated and horizontal, with the words "The", "End", "of", and "the World" clearly distinguishable despite the pixelation. The background is white, and the text itself is a dark gray or black.



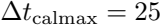


Pravda

$$\eta_{\text{mos}} = \frac{\Delta t_{\text{point/cycle}}}{\Delta t_{\text{point/cycle}} + \Delta t_{\text{slew}}}$$

$$\Delta t_{\text{cycle}} = \Delta t_{\text{point/track}} (\Delta t_{\text{point/cycle}} + \Delta t_{\text{slw}}),$$

$\Delta t_{point/cycle} = \Delta t_{repeat/point/cycle} \Delta t_{int/acc}$



$$n_{\text{repeat/point/cycle}}^{\text{max}} = \frac{\Delta t_{\text{calmax}}/n_{\text{point/track}} - \Delta t_{\text{slew}}}{\Delta t_{\text{int/scan}}},$$

$$\eta_{\text{mos}} = 1 - \frac{n_{\text{point}} / \text{track} \Delta t_{\text{slew}}}{\Delta t_{\text{calmax}}} .$$

$$n_{\text{point/track}}^{\text{large}} = \text{floor} \left(\frac{\Delta t_{\text{calmax}}}{\Delta t_{\text{int/scan}} + \Delta t_{\text{slew}}} \right).$$

1991-2000

$$n_{\text{point}/\text{track}}^{\text{max}} = \frac{\Delta t_{\text{cyclmax}}}{\Delta t_{\text{min}} + \Delta t_{\text{slew}}} \sim 150.$$

$$\Delta t_{\text{int}/\text{scan}} = \min \left\{ \Delta t_{\text{int}/\text{scan}}, \left(\frac{\Delta t_{\text{cyclmax}}}{n_{\text{point}/\text{track}}} - \Delta t_{\text{slew}} \right) \right\}.$$

$$\eta_{\min} = \frac{\Delta t_{\min}}{\Delta t_{\min} + \Delta t_{\text{slew}}} = 0.47.$$

$$n_{\text{beam}} = \frac{A_{\text{map}}}{A_{\text{beam}}}, \quad \text{where} \quad A_{\text{beam}} = \frac{0.8 \pi \theta_{\text{prim}}^2}{4 \ln(2)}.$$

$$n_{\text{point}} = n_{\text{beam}} \left(\frac{7}{4} \right)^2, \quad \text{and} \quad n_{\text{point}/\text{track}} = \min \left(n_{\text{point}}, \frac{n_{\text{point}}}{n_{\text{track}}} \right).$$

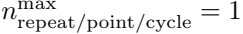
$$10 \text{ sec} \leq \Delta t_{\text{int/scan}} = \min \left(45 \text{ sec}, \eta \frac{6900}{1 \text{ sec}} \sqrt{\frac{\theta_{\text{maj}} \theta_{\text{min}}}{A_{\text{map}}}} \right) \quad \text{with} \quad \eta = 0.5.$$

$$n_{\text{point/track}}^{\text{large}} = \text{floor} \left(\frac{\Delta t_{\text{calmax}}}{\Delta t_{\text{int/scan}} + \Delta t_{\text{slew}}} \right), \quad \text{where} \quad \Delta t_{\text{slew}} = 11 \text{ sec}, \quad \text{and} \quad \Delta t_{\text{calmax}} = 25 \text{ min}.$$

$\left(\text{point/track} \right) \leq \left(\text{large point/track} \right)$

$$n_{\text{repeat/point/cycle}}^{\text{max}} = \frac{\frac{\Delta t_{\text{calmax}}}{n_{\text{point/track}}} - \Delta t_{\text{slew}}}{\Delta t_{\text{int/scan}}}.$$

$\left(\frac{\text{point}}{\text{track}} \right) \rightarrow \left(\frac{\text{large}}{\text{point}} \right) \frac{\text{track}}{\text{track}}$



$$n_{\text{point/track}} \leq n_{\text{point/track}}^{\text{max}}, \quad \text{where} \quad n_{\text{point/track}}^{\text{max}} = \frac{\Delta t_{\text{cyclemax}}}{\Delta t_{\text{min}} + \Delta t_{\text{slew}}} \sim 150, \quad \text{and} \quad \Delta t_{\text{cyclemax}} = 60 \text{ min.}$$

$$\text{if } n_{\text{point/track}} > n_{\text{point/track}}^{\text{large}}, \quad \text{then } \Delta t_{\text{int/scan}} = \min \left\{ \Delta t_{\text{int/scan}}, \left(\frac{\Delta t_{\text{cyclemax}}}{n_{\text{point/track}}} - \Delta t_{\text{slew}} \right) \right\}.$$

$$\eta_{\text{mos}} = \frac{\Delta t_{\text{point/cycle}}}{\Delta t_{\text{point/cycle}} + \Delta t_{\text{slew}}}, \quad \text{and} \quad \Delta t_{\text{point/cycle}} = n_{\text{repeat/point/cycle}}^{\text{max}} \Delta t_{\text{int/scan}},$$

$$\Delta t_{\text{cycle}} = n_{\text{point/track}} (\Delta t_{\text{point/cycle}} + \Delta t_{\text{slew}}).$$

$$\sigma_{\text{Jy}} = \frac{J_{\text{ant}}^{\text{int}} T_{\text{sys}}}{\eta_{\text{spec}} \sqrt{n_{\text{ant}} (n_{\text{ant}} - 1)} d\nu n_{\text{pol}} \Delta t_{\text{on}}}, \quad \text{and} \quad \Delta t_{\text{on}} = \eta_{\text{obs}} \eta_{\text{mos}} \left(\frac{\Delta t_{\text{tel}} - n_{\text{track}} \times \Delta t_{\text{setup}}}{n_{\text{beam}}} \right).$$



$$\sigma_{Jy,\text{point}}(\nu) = \frac{J_{\text{ant}}^{\text{int}}(\nu) T_{\text{sys}}(\nu)}{\eta_{\text{spec}} \sqrt{n_{\text{ant}}(n_{\text{ant}} - 1)} d\nu n_{\text{pol}} \Delta t_{\text{on,point}}},$$

$$\Delta t_{\text{on, point}} = \eta_{\text{obs}} \eta_{\text{mos}} \left(\frac{\Delta t_{\text{tel}} - n_{\text{track}} \times \Delta t_{\text{setup}}}{n_{\text{point}}} \right).$$

100%



$$f_v(p) = \left[\sum_{i=1}^{n_{\text{point}}} B_i^2(p, v) \right]^{-1/2}.$$

опыта, в том числе в области
использования технологий
искусственного интеллекта
и машинного обучения.

$$\sigma_{\text{Jy,mos}}(p, \nu) = \frac{J_{\text{ant}}^{\text{int}}(\nu) T_{\text{sys}}(\nu)}{\eta_{\text{spec}} \sqrt{n_{\text{ant}} (n_{\text{ant}} - 1)} d\nu n_{\text{pol}} \Delta t_{\text{on,point}}} \left[\sum_{i=1}^{n_{\text{point}}} B_i^2(p, \nu) \right]^{-1/2}.$$

As a *wp* is not *blabla*.

of the *Mediaviva* of the *Mediaviva*.

Opportunity is a
= Opportunity is

f = independent variable



Oxytropis, *Oxytropis*, *Oxytropis*

Approved
Valid
Date

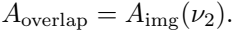
Alvin

Alvin









$$P_{1n2/1} = 100 \frac{A_{\text{img}}(v_2)}{A_{\text{img}}(v_1)}, \quad P_{1n2/2} = 100\%.$$

$$n_{\mathrm{beam,geom}}(\nu) = \frac{A_{\mathrm{img}}(\nu)}{A_{\mathrm{beam}}(\nu)}.$$

$$n_{\text{beam},\text{eq}}(v) = n_{\text{point}} f^2_v.$$



WELCOME TO THE

$$f_{\nu}(p) = \frac{1}{\sqrt{\sum_{i=1}^{n_{\text{point}}} B_{i,\nu}^2(p)}}.$$

Erwählter

$\text{Aimg}(v) = \text{Nvalid}(v) \text{Opix}$

$$f_v = \max_{p \in A_v} [f_v(p)],$$





A_{map}



$A_{img}(v)$

$$n_{\text{point}} = \text{number of pointings in the PMS pointing list, and } n_{\text{point/track}} = \min \left(n_{\text{point}}, \frac{n_{\text{point}}}{n_{\text{track}}} \right).$$

$$n_{\text{point}} = n_{\text{beam}} \left(\frac{7}{4} \right)^2$$

$$\Delta t_{\text{on, point}} = \eta_{\text{obs}} \eta_{\text{mos}} \left(\frac{\Delta t_{\text{tel}} - n_{\text{track}} \times \Delta t_{\text{setup}}}{n_{\text{point}}} \right),$$

$$\sigma_{Jy,point}(\nu) = \frac{J_{ant}^{int}(\nu) T_{sys}(\nu)}{\eta_{spec} \sqrt{n_{ant} (n_{ant} - 1)} d\nu n_{pol} \Delta t_{on,point}} .$$

$$\sigma_{\mathcal{J}_{Y,\text{typ}}}(v) = \sigma_{\mathcal{J}_{Y,\text{point}}}(v) \tilde{f}_v.$$

$$n_{\text{beam},\text{eq}}(v) = n_{\text{point}} f^2_v.$$









$$\Omega_{\text{ant}}(\nu) = \int_{4\pi} P_{\text{ant}}(\theta, \phi, \nu) d\Omega,$$







airbnb

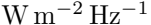


$$\Omega_{\text{fb}}(\nu) = \int_{2\pi} P_{\text{ant}}(\theta, \phi, \nu) d\Omega, \quad \text{and} \quad \Omega_{\text{mb}}(\nu) = \int_{\text{main lobe}} P_{\text{ant}}(\theta, \phi, \nu) d\Omega.$$

$$F_{\text{eff}} = \frac{\Omega_{\text{fb}}}{\Omega_{\text{ant}}}, \quad \text{and} \quad B_{\text{eff}} = \frac{\Omega_{\text{mb}}}{\Omega_{\text{ant}}}.$$

$$F_{\text{sou}}(\nu) = \int_{\text{source}} B(\theta, \phi, \nu) d\Omega,$$











$$F_{\text{obs}}(\theta_0, \phi_0, \nu) = \int_{\text{source}} B(\theta, \phi, \nu) P_{\text{ant}}(\theta - \theta_0, \phi - \phi_0, \nu) d\Omega,$$



$$F_{\text{obs}}(\theta_0, \phi_0, \nu) = \int_{\text{source}} B(\theta, \phi, \nu) \tilde{P}_{\text{ant}}(\theta_0 - \theta, \phi_0 - \phi, \nu) d\Omega,$$

$$P_{\text{int}}(\theta_0 - \theta, \phi_0 - \phi, v) = P_{\text{int}}(\theta - \theta_0, \phi - \phi_0, v).$$

$$B_{\text{obs}}(\theta_0, \phi_0, \nu) = \frac{1}{\Omega} \int_{\text{source}} B(\theta, \phi, \nu) \tilde{P}_{\text{ant}}(\theta_0 - \theta, \phi_0 - \phi, \nu) d\Omega,$$









Is it possible to

$$= \frac{1}{\Omega_{\text{ant}}} \int_{\text{source}} B(\theta, \phi, \nu) \tilde{P}_{\text{ant}}(\theta_0 - \theta, \phi_0 - \phi, \nu) d\Omega,$$

[illegible]

$$= \frac{1}{\Omega_{\text{fb}}} \int_{\text{source}} B(\theta, \phi, \nu) \tilde{P}_{\text{ant}}(\theta_0 - \theta, \phi_0 - \phi, \nu) d\Omega,$$

BEADPOWERS

$$= \frac{1}{\Omega_{\text{mb}}} \int_{\text{source}} B(\theta, \phi, \nu) \tilde{P}_{\text{ant}}(\theta_0 - \theta, \phi_0 - \phi, \nu) d\Omega.$$

$$B_{fb} = \frac{1}{F_{eff}} B_{ant} \quad \text{and} \quad B_{mb} = \frac{F_{eff}}{B_{eff}} B_{fb}.$$

over the world, over the world,















$$T_{\text{mb}}(\theta_0, \phi_0, \nu) = \frac{1}{\Omega_{\text{mb}}} \int_{\text{source}} B(\theta, \phi, \nu) \tilde{P}_{\text{ant}}(\theta_0 - \theta, \phi_0 - \phi, \nu) d\Omega.$$





13059x1021

$$d\nu(\theta_0, \phi_0, \nu) = \frac{1}{2} A_{\text{eff}} \int_{\text{source}} B(\theta, \phi, \nu) \tilde{P}_{\text{ant}}(\theta_0 - \theta, \phi_0 - \phi, \nu) d\Omega.$$





$$\eta_{\text{ant}} = \frac{A_{\text{eff}}}{A_{\text{geo}}} < 1;$$

$$A_{geo} = \pi \left(\frac{D_{ant}}{2} \right)^2 \cdot$$

$$\text{Aeff}(v) \text{ quant}(v) = \lambda^2,$$

$$B(\theta, \phi, \nu) = \frac{2kT}{\lambda^2},$$

$$d\nu(\theta_0, \phi_0, \nu) = \frac{1}{2} A_{\text{eff}} \int_{\text{source}} B(\theta, \phi, \nu) \tilde{P}_{\text{ant}}(\theta_0 - \theta, \phi_0 - \phi, \nu) d\Omega = \frac{1}{2} A_{\text{eff}} \Omega_{\text{ant}}(\nu) \frac{2kT}{\lambda^2}.$$

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$$A_{\text{eff}}(\nu)\Omega_{\text{fb}}(\nu)=\lambda^2 F_{\text{eff}}(\nu) \text{ and } A_{\text{eff}}(\nu)\Omega_{\text{mb}}(\nu)=\lambda^2 B_{\text{eff}}(\nu).$$

$$B_{\text{eff}}(v) = \eta_{\text{ant}} A_{\text{geo}} \frac{\Omega_{\text{mb}}(v)}{\lambda^2} \cdot$$

$$A_{\mathrm{geo}} = \frac{\pi}{4} D^2, \quad \frac{\Omega_{\mathrm{mb}}(\nu)}{\lambda^2} = \frac{\pi}{4 \ln 2} \left(\frac{\theta_{\mathrm{mb}}}{\lambda} \right)^2,$$

$$\theta_{mb} = \alpha \frac{\lambda}{D},$$

$$B_{\text{eff}}(\nu) = \frac{\pi^2}{16 \ln 2} a^2 \eta_{\text{ant}}(\nu) \simeq 0.88899 a^2 \eta_{\text{ant}}(\nu).$$







$$\eta_{\text{ant}}(\nu) = \eta_{\text{ant}}^0 \exp \left\{ - \left(\frac{4\pi\sigma}{\lambda} \right)^2 \right\}.$$

Band 1

Band 3

